Electric Centric Grippers EIG3-65100 3-Finger

- Advantages

 Smooth body

 Precise planetary gear drive

 Grip control: force and position adjustment

 Quick open/close time with speed adjustment

 Grip feedback and part detection: gripper status can be read at the PLC/Controller and visualized on the unit via LED's

 Multiple communication modes: the gripper supports Modbus RTU protocol and IO mode control. Other protocols such as USB and ETHERNET can be implemented through a protocol converter

 Grip actuation via embedded controller.

 Brake locking mechanism



SPECIFICATIONS

Model	Gripping Diameter	Gripping Force per Jaw	Total Gripping Force	Opening/ Closing Time	Nominal Voltage	Nominal Current	Max Current	Repeatability (Positioning)	Recommended Workpiece Weight*	Weight
EIG3-65100	40 - 170 mm 1.6 - 6.7 in	30 - 100 N 6.7 - 22.5 lb	90 - 300 N 20.2 - 67.4 lb		24 V DC ± 10%	0.40 A	1.00 A	± 0.03 mm ± 0.001 in	1.5 kg 3.31 lb	1.5 kg 3.31 lb

^{*} Recommended workpiece weight depends on the shape of the part, the material and friction of the contact surface and the acceleration of the motion.

Communication Interface Standard: Modbus RTU (RS485), Digital I/O Optional: TCP/IP, USB2.0, CAN2.0A, PROFINET, EtherCAT

IP Protection Class IP 40

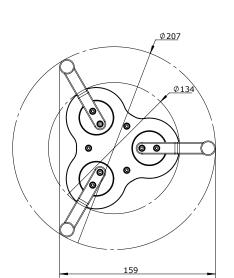
Noise Emission (Sound Pressure) ≤ 40 dB(A) in any direction
Recommended operating environment 0-40 °C (32-104 °F), < 85% RH

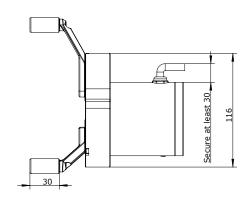
For this type of gripper the use of the standard fingers is recommended.

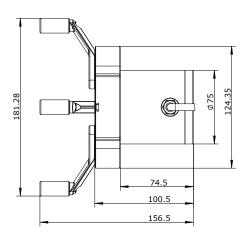


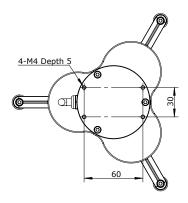
PRODUCT INFORMATION

EIG3-65100 3-Finger











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