

# Worksheet

## Application parameters

Customer:

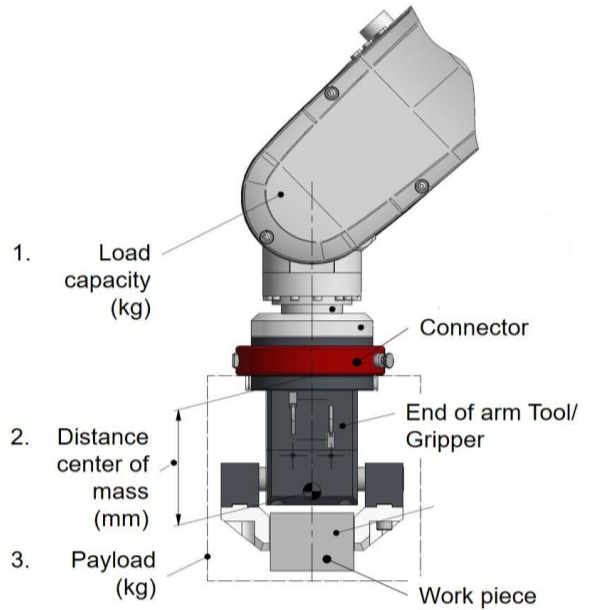
Robot type:

Bolt circle diameter (mm): Please provide a drawing.

Note:

Please enter your corresponding values in the fields highlighted in gray. (Example: 20,2 kg)

- 1.  kg Load capacity of the robot
- 2.  mm Distance of the center of mass from tool/gripper + workpiece to Connector
- 3.  kg Payload on the Connector in the application (end of arm tool/gripper + workpiece)
  
- m/s<sup>2</sup> Maximum acceleration of the end of arm tool/gripper **taking into account an emergency stop**



length ×  height ×  width mm Dimensions of the end of arm tool/gripper for determining the lever arm

Feedthrough:  pneumatic  electrical  vacuum  none

## Base Connector applications:

mm Max extension of the robot arm

Mounting orientation of the Base Connector



horizontal



hanging



vertical