

Quotation and order form parallel indexer (1)

Company _____
 Administrator _____
 Telephone/Fax _____

E-Mail address _____
 Project/Order no. _____
 Date _____

Applications

- Belt or chain conveyor Pivot arm
 Rotation of parts Other (please include drawing)

Belt or chain conveyor

Gear ratio (if applicable) $i =$ _____
 Feed length _____ Distance of deflexion pulleys _____
 Number of work piece carriers _____

Deflexion pulleys

Quantity _____ \varnothing _____ Thickness _____
 Material or weight _____

Belt / Chain

Weight _____ Friction coefficient _____
 Work piece carrier weight _____

Work piece

Quantity _____ Weight _____

Pivot arm

Pivot angle _____ Number of arms _____
 Distance from pivot point to centre of mass of acceptance _____
 Weight of one arm _____
 Weight of fixture and work piece _____

Rotation of parts

Rotation angle _____ Weight of fixture and work piece _____

Stepping operation (cycle time fixed, resting time variable)

Continuous motion (cycle and resting time fixed)

Desired index time [s] $t_s =$ _____

Desired dwell time [s] (continuous motion only) _____

Number of indexes [1/min] _____

Required lifetime (cycle time only, typically 12,000 h) _____

Additional forces and loads (please describe)

Scheibenkurven-Schrittgetriebe

Type XP TP

Frame Size _____

Number of Stops $n =$ _____

Switching angle $\alpha =$ _____

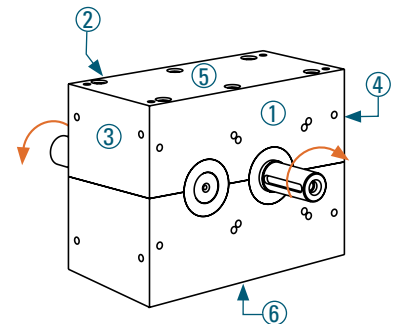
Mounting side of nameplate (Standard 3) _____

Standard Input shaft yes no

If no, deviations _____ mm

Standard output shaft yes no

If no, deviations _____ mm

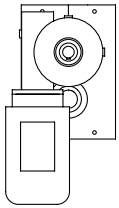


Mounting side of nameplate / Direction of rotation of input and output shaft

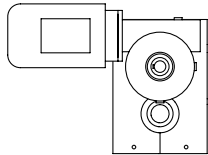
Quotation and order form parallel indexer (2)

Possible mounting positions for the drive units

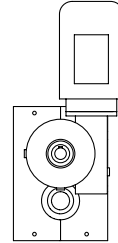
SL-0



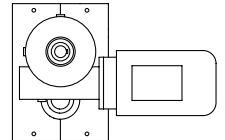
SL-90



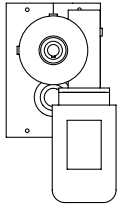
SL-180



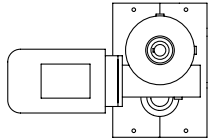
SL-270



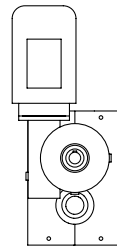
SR-0



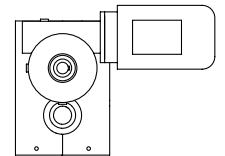
SR-90



SR-180



SR-270



Drive

with Drive without drive

Mounting Position (see above) _____

Terminal Box Position (see right) _____

Voltage Motor 230/400-50 Hz
different Voltage _____

Voltage Brake 24V DC
different Voltage _____

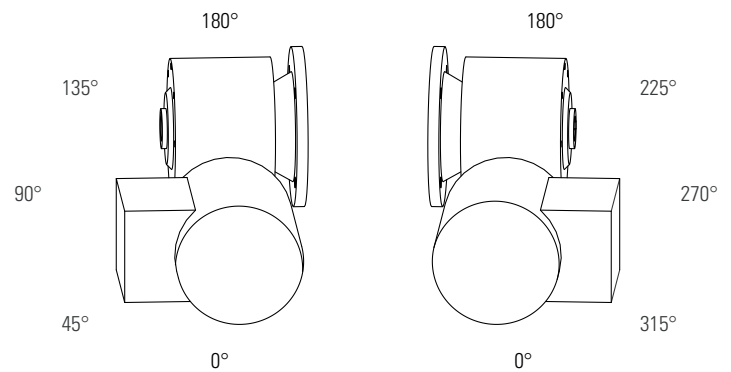
Manual release on brake Yes No

Motor Handwheel Yes No

Input Safety Clutch Yes No

Additional specifications (temperature sensor, connector assembly, brand..)

Terminal Box Position



Universal Controller TIC

Universal Controller TIC Yes No